Attacks on Stream Ciphers: A Perspective

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stream ciphers

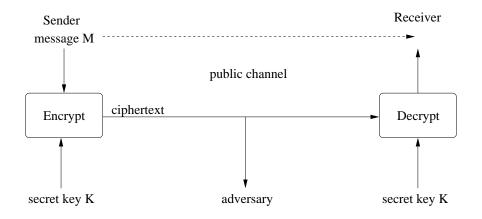
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- Background.
- Correlation Attacks.
- Algebraic Attacks.
- Differential Attacks.
- Time/Memory Trade-Off Attacks.

Background.

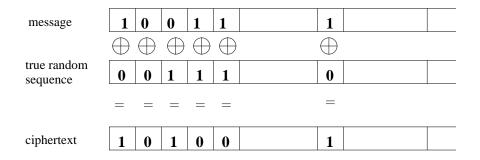
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Model of Symmetric Key Encryption



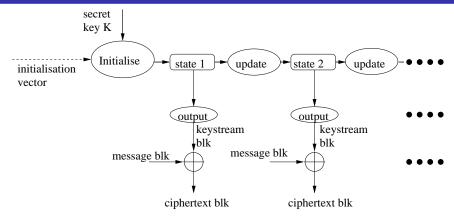
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Model of Additive Stream Cipher



- Key: k bits; IV: (usually) $\leq k$ bits; state: (usually) $\geq 2k$ bits;
- initialise, update, output: functions (deterministic algorithms);
- keystream blk, msg blk, cpr blk: \geq 1 bit.

Self-Synchronizing Stream Cipher

message	m_0	<i>m</i> ₁	m_2	•••	m _i	•••
keystream	k_0	<i>k</i> 1	<i>k</i> ₂	•••	k _i	•••
ciphertext	<i>c</i> ₀	C ₁	<i>c</i> ₂	•••	Ci	•••

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- k_i is completely determined by the secret key K and c_{i-n}, \ldots, c_{i-1} .
- Correctly receiving *n* ciphertext bits allow correct generation of the next keystream bit.
- Robust against channel errors: bit flip/drop/insert.

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 $c_i = m_i \oplus k_i$.

- k_i is completely determined by the secret key K and c_{i-n}, \ldots, c_{i-1} .
- Correctly receiving n ciphertext bits allow correct generation of the next keystream bit.
- Robust against channel errors: bit flip/drop/insert.

More generally, m_i is completely determined by the secret key K and the last n ciphertext bits.

• Ciphertext only attack:

the attacker has access to only ciphertext(s);

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• Known plaintext attack:

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• Known plaintext attack: the attacker *knows* (*P*₁, *C*₁), . . . , (*P*_t, *C*_t);

Chosen plaintext attack:

the attacker chooses P_1, \ldots, P_t ; receives C_1, \ldots, C_t ;

• For additive stream ciphers, this is the same as known plaintext attack.

Attack Models: Adversarial Access (contd.)

- Known/Chosen IV attack: (resynchronization attack) the attacker *knows/chooses* IV₁,...,IV_t; receives the corresponding keystreams.
 - Obtaining keystreams correspond to known plaintexts.
 - IVs are always known.

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Chosen ciphertext attack.

the attacker chooses C_1, \ldots, C_t ; receives P_1, \ldots, P_t ;

- Not very meaningful for usual additive stream ciphers.
- Serious threat for self-synchronising stream ciphers.
- Serious threat for stream ciphers which combine encryption and authentication in a single composite primitive.

Attack Models: Adversarial Goals

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• State recovery:

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- If the state update function is invertible, then this allows to move backwards.
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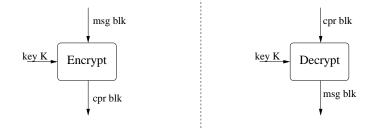
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Distinguishing attack:

- Define a test statistic on a bit string such that the values it takes for uniform random strings and for the real keystream are 'significantly' different.
- Sometimes distinguishing attacks can be converted to key recovery attacks.
- In case of chosen IV attacks, the goal is to distinguish between the set of keystreams and a set of uniform random strings of the same lengths.

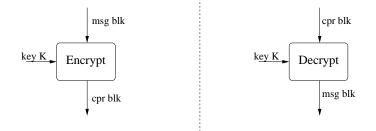
Encrypting Short Fixed Length Strings



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Encrypting Short Fixed Length Strings



Block Cipher.

$$E: \{0,1\}^k \times \{0,1\}^n \to \{0,1\}^n.$$
$$D: \{0,1\}^k \times \{0,1\}^n \to \{0,1\}^n.$$

For each $K \in \{0, 1\}^k$,

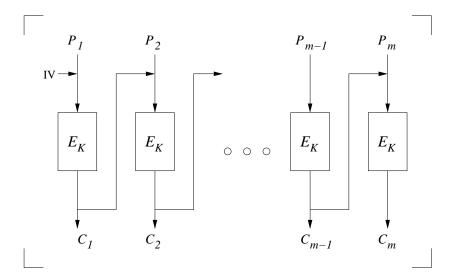
$$D_{\mathcal{K}}(E_{\mathcal{K}}(M)) = M.$$

message: M_1, M_2, M_3, \dots (*n*-bit blocks); **initialization vector:** *n*-bit IV (used as nonce).

Cipher block chaining (CBC) mode: $C_1 = E_K(M_1 \oplus IV);$ $C_i = E_K(M_i \oplus C_{i-1}), i \ge 2.$

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CBC Mode



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Modes of Operations (contd.)

message: M_1, M_2, M_3, \dots (*n*-bit blocks); **initialization vector:** *n*-bit IV (used as nonce).

Output feedback (OFB) mode:

$$egin{aligned} Z_1 &= E_{\mathcal{K}}(\mathrm{IV}); \, Z_i = E_{\mathcal{K}}(Z_{i-1}), \, i \geq 2; \ C_i &= M_i \oplus Z_i, \, i \geq 1. \end{aligned}$$

• This is essentially an additive stream cipher.

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Cipher feedback (CFB) mode:

$$C_1 = M_1 \oplus E_{\mathcal{K}}(\mathrm{IV});$$

$$C_i = M_i \oplus E_K(C_{i-1}), i \geq 2.$$

 Can be used as a self-synchronizing stream cipher in a 1-bit feedback mode.

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Counter (CTR) mode:

 $C_i = M_i \oplus E_{\mathcal{K}}(\text{nonce} || \text{bin}(i)), i \geq 1.$

• Other variants of the CTR mode have been proposed.

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Given (non-zero) initial state (a_0, \ldots, a_{n-1}) generates a sequence

 $a_0, a_1, a_2, \ldots, a_i, \ldots$

where $a_i = c_{n-1}a_{i-1} \oplus \cdots \oplus c_1a_{i-n+1} + c_0a_{i-n}$.

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where $a_i = c_{n-1}a_{i-1} \oplus \cdots \oplus c_1a_{i-n+1} + c_0a_{i-n}$. Characteristic (connection) polynomial:

$$\tau(\mathbf{X}) = \mathbf{X}^n \oplus \mathbf{C}_{n-1} \mathbf{X}^{n-1} \oplus \cdots \oplus \mathbf{C}_1 \mathbf{X} \oplus \mathbf{C}_0.$$

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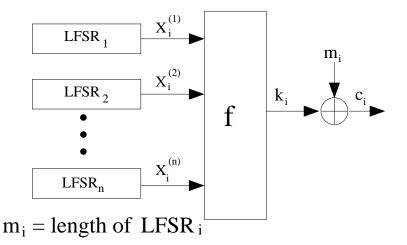
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- If $\tau(x)$ is primitive over GF(2), then the period of $\{a_i\}$ is $2^n 1$.
- Other well-understood "randomness-like" properties.
- Any bit of the sequence is a linear combination of the first *n* bits.
- Given any *n* bits of the sequence, it is easy to get the initial state.
- Unsuitable for direct use in cryptography.

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Nonlinear Combiner Model



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Correlation Attacks.

Correlation Attack

Suppose

$$\Pr\left[X_1^{(i)}=k_i\right]=p\neq\frac{1}{2}.$$

Divide-and-conquer attack.

- Collect ℓ bits of the keystream.
- From each possible 2^{m1} − 1 non-zero initial states of LFSR₁, generate ℓ bits of the LFSR sequence.
- Let *s* be the number of places where the LFSR sequence equals the keystream sequence.
- If s ≈ lp, then the corresponding state is likely to be the correct intial state.
- If s ≈ ℓ/2, then the corresponding state is unlikely to be the correct initial state.

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- In general, if

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then the LFSRs j_1, \ldots, j_r can be attacked simulatenously.

- Leads to Boolean function design criteria and trade-offs.
 - Balancedness.
 - Correlation immunity (resilience).
 - Algebraic degree.
 - Nonlinearity.
 - Other properties: propagation criteria, strict avalanche criteria,

Coding theory framework:

State *S* of an LFSR is expanded to sequence **a** which is perturbed by non-linear noise **e** to obtain ciphertext **c** with $p = \Pr[e_i = 0] \neq 1/2$.

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Given **c**, using suitable decoding technique to obtain *S*.

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- Works well if the number of taps in the LFSR is small.

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- List decoding techniques.

A different view: Reconstruction of linear polynomials.

Bit a_i is a linear combination $a_i = \bigoplus^{m_1-1} w_{i,j}a_j$; where $w_{i,j}$ s can be

j=0

computed from $\tau(x)$.

A different view: Reconstruction of linear polynomials.

Let
$$\mathbf{w}_i = (w_{i,0}, \dots, w_{i,m_1-1})$$
 and define $A(x) = \bigoplus_{j=0}^{m_1-1} x_j a_j$.

- The values a_0, \ldots, a_{m_1-1} define the polynomial and are unknown.
- Then A(x) is a linear polynomial and $a_i = A(\mathbf{w}_i)$ for $i \ge m_1$.

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- *k_i* is a noisy output of the *unknown* polynomial *A*(*x*) evaluated at the *known* point **w**_i.

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- Use of techniques from computational learning theory due to Goldreich, Rubinfeld and Sudan to reconstruct *f* from the *k_is*.
- The application is not straightforward, there are a few tricks involved.

- Correlations between linear functions of several output bits and linear functions of a subset of LFSR bits.
 - For strong enough correlations, a number of stochastic equations may be derived.
 - If the known keystream sequence is long enough, then the equations can be solved.

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 - For strong enough correlations, a number of stochastic equations may be derived.
 - If the known keystream sequence is long enough, then the equations can be solved.
- Keystream (or simply key) correlation: leads to distinguishing attacks.
 - Bias in a particular keystream bit or a linear combination of keystream bits, eg. Pr[k₁₆ = 0] ≠ 1/2. Attack types: multiple keys; or, single key but, multiple IVs.
 - Bias in a subsequence of key bits, eg. $\Pr[k_i = k_{i+3}] \neq 1/2$ for all $i \ge 0$.

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Algebraic Attacks.

Let *L* be the update functions of all the LFSRs.

- Each LFSR is updated using a linear function and let *L* be the applications of these linear functions to the respective states.
- *L* is a linear function on the whole state.

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Let (s_0, \ldots, s_{n-1}) be the *n*-bit state at time *i*. Keystream:

$$f(s_0, \dots, s_{n-1}) = k_i$$

$$f(L(s_0, \dots, s_{n-1})) = k_{i+1}$$

$$f(L^2(s_0, \dots, s_{n-1})) = k_{i+2}$$

Each of the expressions on the left have degree $d \stackrel{\Delta}{=} \deg(f)$.

There are $\sum_{j=1}^{d} {n \choose j}$ monomials of degree at most *d*.

- Replace each monomial by a new variable.
- Solve the resulting system of linear equations.
 - Sufficient number of keystream bits required to get an over-defined system of equations.
- From the solution to the linear system, obtain the solution to the original system.

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Use Gröbner basis based technique to directly solve the system of multivariate polynomial equations over \mathbb{F}_2 .

- Becomes progressively inefficient as *d* increases.
- The linearisation technique also essentially computes the Gröbner basis.

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Suppose g is a function such that $\deg(f \times g) < \deg(g)$. Example: $f(x_1, x_2, x_3) = x_1 \oplus x_2 \oplus x_1 x_2 x_3$ and $g(x_1, x_2, x_3) = x_2 x_3$.

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Controlling the Degree

Suppose g is a function such that $\deg(f \times g) < \deg(g)$. Example: $f(x_1, x_2, x_3) = x_1 \oplus x_2 \oplus x_1 x_2 x_3$ and $g(x_1, x_2, x_3) = x_2 x_3$.

$$\begin{aligned} f(s_0, \dots, s_{n-1})g(s_0, \dots, s_{n-1}) &= k_i \cdot g(s_0, \dots, s_{n-1}) \\ f(L(s_0, \dots, s_{n-1}))g(L(s_0, \dots, s_{n-1})) &= k_{i+1} \cdot g(L(s_0, \dots, s_{n-1})) \\ f(L^2(s_0, \dots, s_{n-1}))g(L^2(s_0, \dots, s_{n-1})) &= k_{i+2} \cdot g(L^2(s_0, \dots, s_{n-1})) \\ & \dots \dots \dots \dots \end{aligned}$$

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$$\begin{aligned} f(s_0, \dots, s_{n-1})g(s_0, \dots, s_{n-1}) &= k_i \cdot g(s_0, \dots, s_{n-1}) \\ f(L(s_0, \dots, s_{n-1}))g(L(s_0, \dots, s_{n-1})) &= k_{i+1} \cdot g(L(s_0, \dots, s_{n-1})) \\ f(L^2(s_0, \dots, s_{n-1}))g(L^2(s_0, \dots, s_{n-1})) &= k_{i+2} \cdot g(L^2(s_0, \dots, s_{n-1})) \\ & \dots \dots \dots \dots \end{aligned}$$

If deg(g) < d or $k_j = 0$ (which happens roughly half of the times), then we get a system of equations whose degrees are less than *d*.

• Finding a "good" *g* is important.

A General Formulation

Let $\mathbf{s} = (s_0, \dots, s_{n-1})$. Find a Boolean function \hat{f} such that for some $\delta \ge 0$ $\widehat{f}(L^t(\mathbf{s}), \dots, L^{t+\delta}(\mathbf{s}), k_t, \dots, k_{t+\delta}) = 0.$

• For $\delta = 0$, take $\hat{f} = f$.

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• For $\delta = 0$, take $\hat{f} = f$. Suppose \hat{f} can be written as

$$\begin{split} \widehat{f}(\mathcal{L}^{t}(\mathbf{s}), \dots, \mathcal{L}^{t+\delta}(\mathbf{s}), k_{t}, \dots, k_{t+\delta}) \\ &= h(\mathcal{L}^{t}(\mathbf{s}), \dots, \mathcal{L}^{t+\delta}(\mathbf{s})) \oplus g(\mathcal{L}^{t}(\mathbf{s}), \dots, \mathcal{L}^{t+\delta}(\mathbf{s}), k_{t}, \dots, k_{t+\delta}) \\ &= h_{t}(\mathbf{s}) \oplus g_{t}(\mathbf{s}, k_{t}, \dots, k_{t+\delta}) \end{split}$$

where the degree e of **s** in g is less than the degree d of **s** in \hat{f} .

Assume that the attacker can find constants c_0, \ldots, c_{T-1} such that

$$\bigoplus_{j=0}^{T-1} c_j h_{t+j}(\mathbf{s}) = 0.$$

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$$0 = \widehat{f}(L^{t}(\mathbf{s}), \ldots, L^{t+\delta}(\mathbf{s}), k_{t}, \ldots, k_{t+\delta}) = h_{t}(\mathbf{s}) \oplus g_{t}(\mathbf{s}, k_{t}, \ldots, k_{t+\delta})$$

we can write

$$\bigoplus_{j=0}^{T-1} c_j g_{t+j}(\mathbf{s}, k_t, \dots, k_{t+\delta}) = 0.$$

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we can write

$$\bigoplus_{j=0}^{T-1} c_j g_{t+j}(\mathbf{s}, k_t, \ldots, k_{t+\delta}) = 0.$$

This is an equation of lower degree e in the unknown s.

A General Formulation (contd.)

Finding the constants c_0, \ldots, c_{T-1} .

- Choose a "reasonable" value **s*** of **s**.
- Compute $\hat{k}_t = h_t(\mathbf{s}^*)$ for t = 0, ..., 2T 1.

Finding the constants c_0, \ldots, c_{T-1} .

- Choose a "reasonable" value **s*** of **s**.
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- Use Berlekamp-Massey algorithm to find c_0, \ldots, c_{T-1} such that

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$$0 = \bigoplus_{j=0}^{T-1} c_j \hat{k}_{t+j}$$
$$= \bigoplus_{j=0}^{T-1} c_j h_{t+j}(\mathbf{s}^*).$$

- Requires $O(T^2)$ time.
- The proof that these c_0, \ldots, c_{T-1} work for all **s** is non-trivial.

Some References: Algebraic Attacks

 N. Courtois, W. Meier: Algebraic Attacks on Stream Ciphers with Linear Feedback. EUROCRYPT 2003.

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Differential Attacks.

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State: $(s_1^{(i)}, \ldots, s_{288}^{(i)})$: (Super-script *i* is omitted for simplicity.)

- State update function is non-linear.
- Output function is linear.

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$$(s_1, s_2, \dots, s_{93}) \leftarrow (t_3, s_1, \dots, s_{92});$$

 $(s_{94}, s_{95} \dots, s_{177}) \leftarrow (t_1, s_{94}, \dots, s_{176});$
 $(s_{178}, s_{179}, \dots, s_{288}) \leftarrow (t_2, s_{178}, \dots, s_{287});$

$$\Delta_{\mathbf{a}}f(\mathbf{x}) \stackrel{\Delta}{=} f(\mathbf{x} \oplus \mathbf{a}) \oplus f(\mathbf{x}).$$

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Extension:

$$\Delta_{\mathbf{a}_1,\mathbf{a}_2}^{(2)}f(\mathbf{x}) = f(\mathbf{x} \oplus \mathbf{a}_1 \oplus \mathbf{a}_2) \oplus f(\mathbf{x} \oplus \mathbf{a}_1) \oplus f(\mathbf{x} \oplus \mathbf{a}_2) \oplus f(\mathbf{x}).$$

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Other direction: $f(\mathbf{x} \oplus \mathbf{a}_1 \oplus \mathbf{a}_2) = \Delta_{\mathbf{a}_1,\mathbf{a}_2}^{(2)} f(\mathbf{x}) \oplus \Delta_{\mathbf{a}_1} f(\mathbf{x}) \oplus \Delta_{\mathbf{a}_2} f(\mathbf{x}) \oplus f(\mathbf{x}).$

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Other direction: $f(\mathbf{x} \oplus \mathbf{a}_1 \oplus \mathbf{a}_2) = \Delta_{\mathbf{a}_1,\mathbf{a}_2}^{(2)} f(\mathbf{x}) \oplus \Delta_{\mathbf{a}_1} f(\mathbf{x}) \oplus \Delta_{\mathbf{a}_2} f(\mathbf{x}) \oplus f(\mathbf{x}).$

$$f(\mathbf{x} \oplus \mathbf{a}_1 \oplus \cdots \oplus \mathbf{a}_n) = \bigoplus_{i=0}^n \bigoplus_{1 \le j_1 < \cdots < j_i \le n} \Delta_{\mathbf{a}_{j_1}, \dots, \mathbf{a}_{j_i}}^{(i)} f(\mathbf{x}).$$

Derivatives (contd.)

Properties.

- $\deg(\Delta_{\mathbf{a}}f) < \deg(f)$.
- $\Delta_{\mathbf{a}_1,\mathbf{a}_2}^{(2)}f(\mathbf{x}) = \Delta_{\mathbf{a}_2,\mathbf{a}_1}^{(2)}f(\mathbf{x}).$
- $\Delta_{\mathbf{a}}(f \oplus g) = \Delta_{\mathbf{a}}f \oplus \Delta_{\mathbf{a}}g.$
- $\Delta_{\mathbf{a}}(f(\mathbf{x})g(\mathbf{x})) = f(\mathbf{x} \oplus \mathbf{a})\Delta_{\mathbf{a}}g(\mathbf{x}) \oplus (\Delta_{\mathbf{a}}f(\mathbf{x}))g(\mathbf{x}).$
- If $\mathbf{a} \in \{0,1\}^n$ is such that $\operatorname{supp}(\mathbf{a}) \subset \{1,\ldots,i\}$, then

$$\Delta_{\mathbf{a}}(x_1\cdots x_i f(x_{i+1},\ldots,x_n)) = f(x_{i+1},\ldots,x_n) \Delta_{\mathbf{a}}(x_1\cdots x_i).$$

Derivatives (contd.)

Properties.

- deg(Δ_af) < deg(f).
 Δ⁽²⁾_{a₁,a₂}f(**x**) = Δ⁽²⁾_{a₂,a₁}f(**x**).
 Δ_a(f ⊕ g) = Δ_af ⊕ Δ_ag.
 Δ_a(f(**x**)g(**x**)) = f(**x** ⊕ **a**)Δ_ag(**x**) ⊕ (Δ_af(**x**))g(**x**).
 If **a** ∈ {0,1}ⁿ is such that supp(**a**) ⊂ {1,...,i}, then Δ_a(x₁ ··· x_if(x_{i+1},...,x_n)) = f(x_{i+1},...,x_n)Δ_a(x₁ ··· x_i).
 - Nothing special about $x_1 \cdots x_i$; easy modification for the monomial $x_{j_1} \cdots x_{j_i}$.

Let C[a₁,..., a_i] be the set of all linear combinations of a₁,..., a_i.
 Then

$$\Delta^{(i)}_{\mathbf{a}_1,...,\mathbf{a}_i} f(\mathbf{X}) = igoplus_{\mathbf{c} \in C[\mathbf{a}_1,...,\mathbf{a}_i]} f(\mathbf{X} \oplus \mathbf{c}).$$

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$$\Delta^{(i)}_{\mathbf{a}_1,...,\mathbf{a}_i}f(\mathbf{x}) = igoplus_{\mathbf{c}\in C[\mathbf{a}_1,...,\mathbf{a}_i]}f(\mathbf{x}\oplus\mathbf{c}).$$

• If \mathbf{a}_i is linearly dependent on $\mathbf{a}_1, \ldots, \mathbf{a}_{i-1}$, then $\Delta_{\mathbf{a}_1,\ldots,\mathbf{a}_i}^{(i)} f(\mathbf{x}) = 0$.

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Suppose $f(x_1, \ldots, x_n)$ can be written as

$$f(x_1,\ldots,x_n)=x_1\cdots x_ig(x_{i+1},\ldots,x_n)\oplus h(x_1,\ldots,x_n)$$

where $x_1 \cdots x_i$ does not divide any monomial of $h(x_1, \dots, x_n)$.

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Let $\mathbf{a}_1, \ldots, \mathbf{a}_i$ be linearly independent vectors such that $\operatorname{supp}(\mathbf{a}_1), \ldots, \operatorname{supp}(\mathbf{a}_i) \subset \{1, \ldots, i\}.$

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Let $\mathbf{a}_1, \ldots, \mathbf{a}_i$ be linearly independent vectors such that $\operatorname{supp}(\mathbf{a}_1), \ldots, \operatorname{supp}(\mathbf{a}_i) \subset \{1, \ldots, i\}$. Then

$$g(\mathbf{x}_{i+1},\ldots,\mathbf{x}_n) = \Delta_{\mathbf{a}_1,\ldots,\mathbf{a}_i} f(\mathbf{x}_1,\ldots,\mathbf{x}_n)$$

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$$= \bigoplus_{\mathbf{c}\in C[\mathbf{a}_1,\ldots,\mathbf{a}_i]} f(\mathbf{x}\oplus\mathbf{c}).$$

Nothing special about $x_1 \cdots x_i$; easy modification for $x_{j_1} \cdots x_{j_i}$.

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Using Derivatives (contd.)

Maxterm: $x_{j_1} \cdots x_{j_i}$ is a maxterm if the corresponding *g* is of degree 1.

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Suppose $x_1 \cdots x_i$ is a maxterm.

$$f(\mathbf{x}) = x_1 \cdots x_i g(x_{i+1}, \dots, x_n) + h(\mathbf{x}).$$

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Constant term of g is obtained by setting x_{i+1},..., x_n to 0 and XORing together the values of f for all possible choices of x₁,..., x_i.

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Suppose $x_1 \cdots x_i$ is a maxterm.

$$f(\mathbf{x}) = x_1 \cdots x_i g(x_{i+1}, \dots, x_n) + h(\mathbf{x}).$$

- Constant term of g is obtained by setting x_{i+1},..., x_n to 0 and XORing together the values of f for all possible choices of x₁,..., x_i.
- The coefficient of x_j in g (j > i) is obtained by setting x_j to 1, all other x_{i+1},..., x_n to 0 and XORing together the values of f for all possible choices of x₁,..., x_i.

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- The coefficient of x_j in g (j > i) is obtained by setting x_j to 1, all other x_{i+1},..., x_n to 0 and XORing together the values of f for all possible choices of x₁,..., x_i.

Nothing special about $x_1 \cdots x_i$; easy modification for $x_{j_1} \cdots x_{j_i}$.

Consider a stream cipher with secret key $K = (\kappa_1, \ldots, \kappa_n)$ and $IV = (v_1, \ldots, v_m)$.

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Let *A* be an $n \times n$ matrix representing these linear functions. It can be ensured with high probability that *A* is invertible.

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$$g(K, v_d, \dots, v_m) = \bigoplus_{\mathbf{c} \in C[\mathbf{a}_1, \dots, \mathbf{a}_{d-1}]} f((K, \mathrm{IV}) \oplus \mathbf{c})$$
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Obtaining the outputs of f on 2^{d-1} chosen IVs gives the value of g(K, 0, ..., 0) for the unknown K. Obtain the values of $g_1(K, 0, ..., 0), ..., g_n(K, 0, ..., 0)$. Use the previously computed A^{-1} to solve the system of linear equations and obtain the secret key K.

- Exponential in *d* in both the pre-processing and the online phases.
 - Works well when *d* is small.

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- Variants of the attack have been proposed.

- X. Lai. Higher Order Derivatives and Differential Cryptanalysis. Communications and Cryptography, 1992.
- A.Canteaut, M. Videau: Degree of Composition of Highly Nonlinear Functions and Applications to Higher Order Differential Cryptanalysis. EUROCRYPT 2002.

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Time/Memory Trade-Off Attacks

Inverting a One-Way Function

Let *S* be a finite set with #S = N and

$$f: S \rightarrow S$$

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- Memory *N*; time constant.
 - Pre-compute a table of all *N* pairs (x, y) such that f(x) = y.
 - Store the table sorted on the second column.
 - Given a target y_0 , look up the table to find a pre-image.

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- Memory constant; time N.
 - Given target y_0 , compute f(x) for each $x \in S$ until y_0 is obtained.

Basic idea.

- Perform a one-time computation of *N* invocations of *f*.
- Store a table of size *M*.
- Given a particular target y_0 , in time T obtain a pre-image.

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A trade-off point: $T = M = N^{2/3}$.

Pre-computation time is *N* which would make the attack inadmissible.

$$f: S \rightarrow S.$$

Given: y_1, \ldots, y_D . **Goal:** Invert *any one* of these points, i.e., obtain an *x* such that $f(x) = y_i$ for some *i*.

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$$TM^2D^2 = N^2$$
; $1 \le D^2 \le T$; $P = N/D$.

- Pre-computation time: P = N/D.
- Memory *M* and online time satisfy the equation $TM^2 = (N/D)^2$.
- A trade-off point: $D = N^{1/4}$; $P = N^{3/4}$; $T = M = N^{1/2}$.
- All the parameters *D*, *P*, *T*, *M* are less than *N* which makes the attack admissible.

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- Suppose *K* is *k* bits long.
- If s < 2k, then $T = 2^{s/2} < 2^k$.
- Ignoring pre-computation time, this is an attack.
- Counter-measure: state size must be double that of secret key size.

 $f : (K, IV) \mapsto (k + v)$ -bit prefix of the keystream.

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- Ignoring pre-computation time, if v < k, then T < 2^k and we have a valid attack.
- Counter-measure: IV should be at least as large as the key.
- If v < k/3, then P < 2^k and we have a valid attack even considering pre-computation.

- A secure stream cipher will become popular and will be widely deployed.
- Users will choose random secret keys.
- Encryption will be done using the secret key and an IV.
- Restriction on the IV: should not be repeated for the same key.
- To obtain higher security, a user may choose a secret key for each session.
 - Each message in a session would be encrypted using a distinct IV.
 - Same restriction: do not repeat IV for the same key.

Multi-User (In)security

Set IV to a fixed value v and define the map

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- Works for all *k*; but, the effect is less dramatic.

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Some References: TMTO Attacks

• M. E. Hellman: A Cryptanalytic Time-Memory Trade-Off. IEEE Trans. on Infor. Th., 26 (1980).

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- J. Dj. Golic: Cryptanalysis of Alleged A5 Stream Cipher. EUROCRYPT 1997.
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- S. Chatterjee, A. Menezes and P. Sarkar. Another Look at Tightness. SAC 2011, to appear.

• A brief background on stream ciphers.

- Additive and self-synchornizing stream ciphers.
- Attack models and goals.
- Block cipher modes of operations.
- LFSR and non-linear combiner model.
- Correlation Attacks.
- Algebraic Attacks.
- Chosen IV differential attacks.
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We have left out a lot of topics including some *important* ones.

Thank you for your attention!